MXET - MULTIDISCIPI ENGR TECH

MXET 600 Mechatronics II
Credits 3. 2 Lecture Hours. 3 Lab Hours.
Focus on up-to-date knowledge and theories on robotic manipulation and industrial robots; exploration of rigidbody motions, forward and inverse kinematics, differential kinematics, forward and inverse dynamics of robotic manipulator, motion planning and control theories.